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An energy model for the transient flow boiling crisis under highly subcooled conditions at atmospheric pressure Nop R.^{a, b, c}, Duluc M.-C.^{b, d}, Dorville N.^a, Kossolapov A.^c, Chavagnat F.^c, and Bucci M.^c ^aUniversité Paris-Saclay, CEA, Service de thermo-hydraulique et de mécanique des fluides, 91191, Gif-sur-Yvette, ^bUniversité Paris-Saclay, CNRS, Laboratoire Interdisciplinaire des Sciences du Numériques, 91400, Orsay, France. ^cDepartment of Nuclear Science and Engineering, Massachusetts Institute of Technology, Cambridge MA 02139, USA

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10 Abstract

9

We present an original model describing the transient flow boiling crisis of water at high subcooling 11 and atmospheric pressure. We hypothesize that in such conditions, the mechanism of the boiling 12 crisis is the prevention of the bubbles recondensation when a thin fluid layer near the heated wall 13 reaches temperature saturation conditions. To capture this phenomenon, we propose an energy 14 model describing the heat exchanges in the thin fluid layer throughout the entire transient from the 15 initiation to the boiling crisis. We bring to light a non-dimensional mathematical relation capturing 16 168 working points in the investigated range of power escalation period (from 5 to 500 ms), subcooling 17 (from 25 to 75 K) and Reynolds number (8,500 to 35,000) at atmospheric pressure. Its fitting accuracy 18 is excellent for the high subcooling (50 K and above): more than 75 % of these points are predicted 19 with \pm 5 % error. This relationship enables the prediction of the transient critical heat flux based 20 on the steady-state value or a single tuning constant. The non-dimensional groups deduced from the 21 study are relevant tools to identify the major physical phenomena involved in transient boiling crisis 22 and to quantify the impact of the different operating parameters. 23

Keywords: Subcooled flow boiling crisis, Critical Heat Flux, Exponential power escalation, Critical
 energy model

26 Nomenclature

27 Roman letters

28	c_p	Specific heat	$[J.kg^{-1}.K^{-1}]$
29	е	Channel half width	[m]
30	$E^{\prime\prime\prime}$	Energy density rise	$[J.m^{-3}]$
31	$E_0^{\prime\prime\prime}$	Bulk energy density	$[J.m^{-3}]$
32	$E_{cr}^{\prime\prime\prime}$	Critical energy density rise	$[J.m^{-3}]$
33	L	Heated length	[m]
34	N_x	Streamwise characteristic number of the mantle	[—]
35	N_y	Transverse characteristic number of the mantle	[—]
36	Р	Probability density function of turbulent velocity fluctuations	[—]
37	p	Pressure	[bar]
38	Pr	Prandtl number	[—]
39	$q_w^{\prime\prime}$	Heat flux to water	$[W.m^{-2}]$
40	Re	Reynolds number	[—]
41	Re_{τ}	Wall Reynolds number	[—]
42	u^*	Wall shear velocity	$[m.s^{-1}]$
43	u_m	Mean velocity in the streamwise direction within the mantle (Eq. 1)	2) $[m.s^{-1}]$
44	v_m	Characteristic transverse velocity in the mantle (Eq. 19)	$[m.s^{-1}]$
45	Greek letters		
46	α	Thermal diffusivity	$[m^2.s^{-1}]$
47	ΔT_{sub}	Subcooling	[K]
48	δ	Mantle thickness	[m]

49 $\delta_ u = u/u^*$	Viscous sublayer unit	[m]
50 $\delta_T = \delta_{ u}/Pr$	Thermal sublayer unit	[m]
51 <i>λ</i>	Heat removal ratio at steady-state (Eq. 23)	[-]
52 V	Kinematic viscosity	$[m^2.s^{-1}]$
53 <i>p</i> l	Liquid density	$[kg.m^{-3}]$
54 T	Period of the exponential power excursion	[s]
55 $ au_x = L/u_{m,\infty}$	Time scale of the streamwise advection	[s]
56 Superscript		
57 *	Normalized variables relevant to the model (Eq. 10)	
₅₈ +	Quantity normalized with the viscous sublayer Unit	
₅₉ ++	Quantity normalized with the thermal sublayer unit	
60 Subscript		
⁶¹ ∞	Steady-state (related to δ when τ tending to infinity)	
62 <i>SS</i>	Steady-state	
63 Acronym		
64 CHF	Critical Heat Flux	
65 DNS	Direct Numerical Simulation	
66 FDNB	Fully Developed Nucleate Boiling	
67 HSIR	High Speed InfraRed Camera	
68 HSV	High Speed Visible Camera	
69 ITO	Indium Tin Oxide	
70 LSD	Liquid Sublayer Dryout	
71 NCC	Nucleation-Condensation Cycle	

72 ONB	Onset of Nucleate Boiling
73 OV	Overshoot
74 PDF	Probability Density Function
75 PWR	Pressurized Water Reactor

76 1 Introduction

In case of a fast insertion of reactivity in the core of a nuclear reactor important enough to reach 77 a prompt-critical state, e.q. due to a rapid ejection of the control rods, the reactor power can in-78 crease drastically. The heat generation inside the nuclear rods may increase exponentially in time as 79 $q''' \propto e^{t/\tau}$, with the power escalation period τ resulting from the reactivity inserted and the neutronic 80 characteristics of the reactor. This time scale ranges from a few to a few hundreds milliseconds. The 81 power escalation can be mitigated by different neutronic feedback effects. In reactors with low-82 enriched fuel such as Pressurized Water Reactors (PWRs), the Doppler effect is typically sufficient 83 to mitigate the power escalation before reaching a temperature level sufficient to cause fuel damage. 84 Conversely, in most pool-type research reactors, the fuel is highly enriched (20 % and higher) and 85 the Doppler effect may not have a sufficiently strong impact. The dominant neutronic feedback is 86 instead the so-called moderator effect due to the water density, which is largely emphasized when 87 vapor phase, *i.e.* void, is produced. The reader interested in the relevant neutronic feedback in such 88 scenario may refer to the book of Wu [1]. In most pool-type reactors, low pressure (a few bars) 89 and high subcooling (50 K or higher) facilitate the production of void during nucleate boiling. This 90 regime is the most desirable one for nuclear safety during these transients as it allows a high heat 91 removal combined with strong vapor production, which introduces a favorable reactivity feedback. 92 However, a too severe power escalation may lead to the boiling crisis and the transition to film 93 boiling would have two consequences. The void production, *i.e.* vapor, is drastically reduced and 94 so the power mitigation. The heat removal is also deteriorated triggering a significant temperature 95 rise of the fuel rod which could possibly lead to its failure. This accidental scenario is the so-called 96 BORAX-type accident. For this reason, an accurate prediction and a better physical understanding 97 of the boiling crisis under pool-type reactor conditions and under an exponential power excursion is 98 a key issue for nuclear safety. 99

Several full size reactors have been developed in the past to investigate thermohydraulic phenom-101 ena induced by exponentially heating conditions: BORAX [2], SPERT-I [3] and SPERT-IV [4] in the 102 USA, NSRR [5] in Japan and CABRI [6] in France. These experiments provide a realistic overview 103 of the system behavior during such accidental scenarii, as they are real nuclear cores which combine 104 thermal hydraulics and neutronics coupling. However, these integral experiments are extremely ex-105 pensive to design and build and local information on temperature or heat flux fields is inherently 106 unavailable, nor photographic access to observe bubble dynamics. The need to gather this kind of 107 information has led to the development of small-size experiments. Only a few works investigated 108 flow boiling crisis of water at atmospheric pressure under exponential power escalation, e.g. Johnson 109 [7], Kataoka et al. [8] and Kossolapov et al. [9]. Johnson used resistance-based diagnostic giving 110 a mean temperature and heat flux at the wall and X-ray radiography to estimate the void fraction 111 near the heating wall. Kataoka et al. also used resistance-based diagnostic for thermal information. 112 Recently, Kossolapov et al. provided a fine observation of the process leading to boiling crisis in such 113 conditions using high-speed video and infrared thermometry with high spatial resolution. 114

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Most of the modeling efforts regarding the flow boiling crisis focused on steady-state conditions. 116 Many reviews on the subject have been published *e.g.* by Celata [10, 11], Kandlikar [12], Zhang and 117 Mudawar [13] or Ahmed [14]. In the last decades, one of the most featured approach is the so-called 118 Liquid Sublayer Dryout (LSD) assuming that bubbles generated at the wall depart and form vapor 119 blankets which are then advected by the flow. The latter are located in a superheated fluid layer and 120 separated from the heating wall by a liquid layer called liquid sublayer, or macrolayer. The boiling 121 crisis is assumed to occur when the heat flux at the wall is high enough to vaporize the entire liquid 122 sublayer during the transit of a vapor blanket. Inspired by the original work of Haramura and Katto 123 [15] who investigated the saturated pool and flow boiling conditions, Lee & Mudawar [16] and then 124 Katto [17] extended this idea to subcooled flow boiling. Celata [18], starting from a similar model, 125 used thorough physical considerations to improve this approach and circumvent the experimental 126 tuning constants. 127

However, CHF models dedicated to transient heating conditions are scarce. To extend the applicability of steady-state LSD models, Serizawa [19] proposed to explain the generally observed enhancement between the transient and the steady-state CHF by the time needed to vaporize the liquid sublayer. The problem is then reduced to the determination of this time scale. This model makes use of several constants which must be determined through experiments. A few years later, Pasamehmetoglu [20] ¹³³ improved the model, in particular by including turbulence effects of the flow. Besides, due to the ¹³⁴ limitations of instrumentation at that time, experimental data used by Serizawa and Pasamehme-¹³⁵ toglu to develop their models were intrinsically space-averaged values. For fast transients, these ¹³⁶ averaged values only provide limited information. The Liquid Sublayer Dryout phenomenology was ¹³⁷ then generalized for conditions for which no experimental observation of the mechanism involved in ¹³⁸ the boiling crisis could be done, *e.g.* bubbles do not necessarily depart.

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The work of Kossolapov et al. [9] gives a new insight on the underlying mechanisms. It reveals in particular that, for high subcoolings, neither departure of the bubbles from the wall to the core of the flow, nor the formation of vapor blankets are observed. Therefore, the LSD approach used by Serizawa [19] and Pasamehmetoglu [20] as described above is not applicable for highly subcooled conditions which are yet relevant for pool-type research reactors. In summary, there seem to be no models applicable to BORAX-type accidents in highly subcooled water. Filling this gap is of key importance for nuclear safety.

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Based on our understanding of the data gathered by Kossolapov et al., we propose a new model 148 for the description of the transient boiling crisis, suitable for forced convection, highly subcooled flow 149 and exponentially escalating heat inputs. The present paper first describes the phenomenology of 150 the boiling heat transfer in these conditions. This description is used to identify the relevant physical 151 phenomena and to develop a phenomenology of the boiling crisis. A mathematical formulation of 152 the model is then proposed and discussed using physical considerations. Lastly, the effect on boiling 153 crisis of the main experimental parameters (subcooling, mass flow rate, power exponential period) is 154 examined in the light of non-dimensional groups introduced in the model. 155

¹⁵⁶ 2 Experimental observations and interpretations

In this paper, we use the experimental data discussed in Kossolapov et al. [9]. Details about the experimental facility, the diagnostics and the uncertainties of the experimental data can be found in Ref [9]. Briefly, these experiments were conducted in a 1 x 3 cm^2 rectangular cross section channel. The heater is located in one of the channel side, and is made of a 2 x 2 cm^2 square, 1mm-thick sapphire substrate coated by a film of ITO 0.7 μm thick. The latter is placed roughly 65 hydraulic diameters downstream the channel entrance to ensure a fully developed dynamic turbulent boundary layer [21]. The power input is generated by Joule effect in the ITO, electrically conductive, and the effective heating surface is a 1 x 1 cm^2 square. The experiments were diagnosed by a high-speed IR camera (2500 FPS) located behind the heater. The latter is synchronized with a high-speed video camera (20000 FPS) placed front of the heater for visualization. The post processing of the IR camera data, presented in [22], enables to measure the time-dependent distributions on the heating wall of the temperature and the heat flux released to the water as well as their space average quantity $T_w(t)$ and $q''_w(t)$.

170 2.1 Transient boiling crisis for high Reynolds numbers and high sub 171 coolings

A large variety of tests have been conducted in order to investigate the impact on the critical heat 172 flux of several relevant parameters: flow conditions, subcooling and exponential escalation period. 173 As reported in Kossolapov et al. [9], for a high subcooling ($\Delta T_{sub} \geq 50$ K), the heating wall is 174 homogeneously covered by numerous tiny bubbles (about 100 μm in diameter) of short life-time (less 175 than 100 μs). This behavior is not taken into account in the boiling crisis models of the literature. 176 Yet, these conditions of high subcooling combined with forced flow are particularly relevant for 177 experimental nuclear reactor safety and need to be further investigated. Plus, in order to assess the 178 validity limit of the phenomenology, we decide to consider a smaller subcooling equal to 25 K. To 179 summarize, we investigate the flow boiling crisis of water at atmospheric pressure in the following 180 range: 181

- Power escalation period, from 5 ms to 500 ms.
- Subcooling, from 25 K to 75 K.
- Reynolds number, from 8500 to 35000.

¹⁸⁵ In Figure 1, we illustrate the transient path for such conditions with the associated transient boiling ¹⁸⁶ curve. Pictures of the boiling process as recorded by the HSV camera, are presented for the different ¹⁸⁷ stages of the transient boiling curve and described hereafter.

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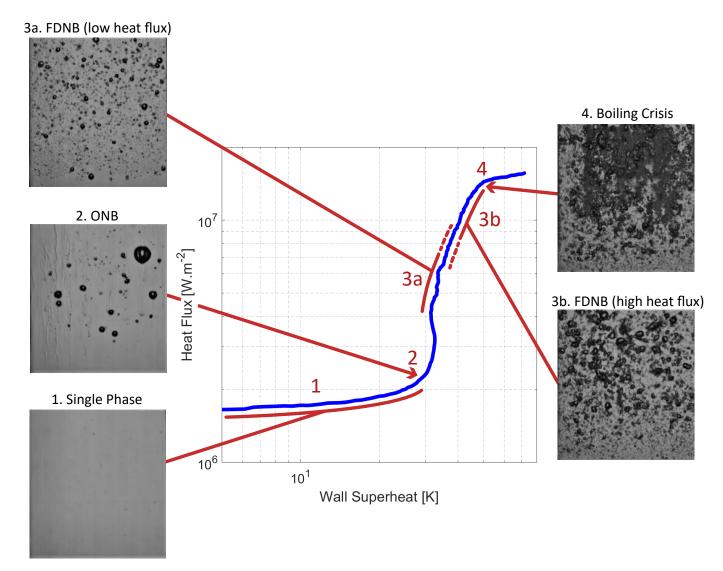


Figure 1: Illustration of the time sequence of the transient heating from single phase to the boiling crisis. HSV images illustrate the successive regimes and each square represents the whole surface of the heater (1cm x 1cm) for the case p = 1 bar, $\Delta T_{sub} = 75$ K, Re = 35000, $\tau = 50$ ms.

189 1. Single-phase regime

Single phase heat transfer is realized in the subcooled water and results from the cumulative actions of the turbulent convection processes and the transient heat conduction. Further information on this regime may be found in the recent work of Chavagnat et al. [23]. Nevertheless, the heat flux to water is still low at this stage (point 1 in Figure 1).

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¹⁹⁵ 2. Onset of Nucleate Boiling and Overshoot

Boiling incipience occurs once the temperature at the heated wall is large enough to activate the nucleation sites. A rapid transient heat input at high subcooling often leads to a temperature overshoot (OV). This phenomenon is widely reported in the literature (Rosenthal [24], Sakurai & Shiotsu [25, 26], Su et. al. [27, 28]). One may observe on the boiling curve a wall superheat higher than in steady-state conditions. In figure 1, the OV is slightly visible as the transient is relatively slow. This overshoot effect is a temporary process. It is linked to the time lag required for activation of the nucleation sites. It increases with the heat generation rate.

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3. Fully Developed Nucleate Boiling

After the overshoot, most of the nucleation sites are activated and the wall appears to be homoge-205 neously covered by bubbles. As reported in Kossolapov et al. [9], e.q. in Fig. 6 of the reference, the 206 bubble diameter decreases with the increase of the subcooling and can be as small as about 100 μm . 207 Moreover, our HSV analysis shows that, in high subcooling conditions, have a short lifetime, about 208 100 μs . Qualitatively, this can be explained considering that bubbles grow up to a small diameter 209 then rapidly collapse due to the cold surrounding water. More interestingly, the HSV reveals a pulsat-210 ing bubble behavior. Bubbles continuously grow and collapse with a frequency greater than 10 kHz. 211 In addition, videos show that bubbles hardly lift-off their nucleation site but remain confined at the 212 vicinity of the wall. It is worth to note that for $\Delta T_{sub} = 25 K$, condition used to assess the validity 213 limit, this mechanism is less pronounced, bubbles have a longer lifetime, about a few milliseconds, 214 and have a width up to 3 mm. Bubbles with such dimensions are not necessarily spherical. This 215 process is observed during the entire Fully Developed Nucleate Boiling (FDNB) regime, the density 216 of bubbles increasing with the heat flux. This evolution is illustrated by HSV images in figure 1 where 217 the density of bubbles is seen to increase from point 3a to 3b. The period of the power escalation 218 does not qualitatively change this behavior. 219

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4. Boiling Crisis

As the heat flux increases, bubbles become more and more numerous on the wall. Local and intermit-222 tent dry spots occur due to lateral coalescence of some neighboring bubbles. These dry spots may be 223 reversible, *i.e.* the wall can be rewetted. However, as the heat transferred from the heating surface 224 to the fluid increases, the lateral coalescence of the neighboring bubbles leads to the formation of 225 irreversible dry spots, *i.e.* to the boiling crisis (point 4 in Figure 1). According to observations made 226 from both HSV and IR camera, the spatio-temporal dynamics of the dry spots changes with the time 227 period τ . For fast transients, dry spots appear uniformly on the entire heating wall. Conversely, for 228 longer transients, dry spots seem to preferentially appear downstream the heating wall, as illustrated 229 by point 4 in Figure 1. This observation will be interpreted in section 4.3 in regard of the model 230 developed in the present work. The transition between fast and slow transients mainly depends on 231 the imposed flow regime, occurring at about 20 ms for high flow rate and 100 ms for low flow rate. 232

234 2.2 Physical description of the model

Considering the observations reported in the former section, we propose to model the boiling cri-235 sis by the following mechanism: boiling crisis is triggered when bubbles generated at the wall can 236 no longer condense in the surrounding liquid, then coalesce laterally generating irreversible dry-237 spots. Indeed, under conditions of high subcooling and strong forced convection, the observations 238 reveal that each bubble grows, then condenses in the surrounding cold liquid and finally disappears. 239 Subsequently, other bubbles are generated at the wall and the process is repeated. One observes 240 Nucleation and Condensation Cycles (NCC) happening at high frequency (about 10 kHz). These 241 NCCs contribute to an efficient heat transfer from the wall to the liquid. Heat released by the 242 condensing bubbles contribute to increase the sensible heat of the liquid. When the liquid reaches 243 the saturation temperature, nucleated bubbles cannot condense anymore triggering the boiling crisis. 244 245

We recall that the investigated conditions are high subcooling and strong forced flow (high 246 Reynolds number). Consequently, the bubbles remain small and constrained at the wall by the 247 shear stress as detailed in section 2.1. Then most of the physical phenomena relevant to this inves-248 tigation will take place in a small layer of fluid at the vicinity of the wall. This is where the NCCs 249 take place: it includes the bubbles and the adjacent liquid in which they condense. This layer will 250 be hereafter called the "mantle" and its thickness will be denoted δ . Besides, bubble growth and 251 collapse induce a highly efficient mixing which contributes to homogenize the temperature of the 252 liquid in the mantle thickness. Considering its definition and the phenomena involved within it, the 253 mantle is a different concept than a conductive sublayer or a classic thermal boundary layer. Once 254 the liquid in the mantle reaches the saturation temperature, the bubbles can no longer condense. 255 This condition will then be considered as a quantitative criterion for the triggering of the boiling 256 crisis. This scenario is schematically summarized in Figure 2 and sequentially described hereafter. 257

The transient process starts with single-phase forced convection until the first bubble appears on the heated wall (ONB). During FDNB, bubbles have a pulsating behavior. They are small and promptly collapse after their nucleation leading to high frequency Nucleation and Condensation Cycles (NCC). These effects are only perceptible near the wall. The model postulates that the highly

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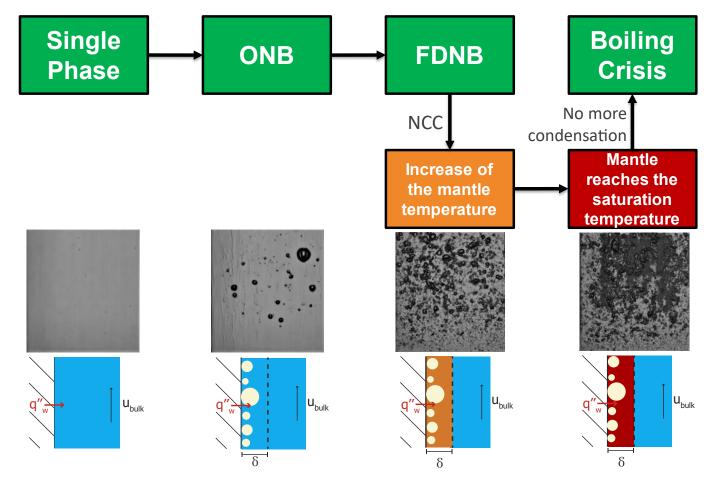


Figure 2: Interpretation of successive events leading to boiling crisis in conditions of high subcooling and strong forced convection. Front backlit shadowgraphy images correspond to the case p = 1 bar, $\Delta T_{sub} = 75$ K, Re = 35000, $\tau = 50$ ms and represent the entire heating surface (1 cm x 1 cm). The bottom schemas illustrate the model considerations with a side view.

efficient mixing induced by NCCs leads to the homogenization of the energy throughout the thickness of the mantle, *i.e.* in the direction normal to the wall. This thickness δ is assumed to be constant throughout the transient process. This assumption is statistically reasonable considering that the mantle is defined as the region dominated by the influence of pulsating bubbles and the size of these bubbles does not significantly change during FDNB (see pictures 3a, 3b and 4 in Figure 1). A second major assumption considers that the thickness δ is also assumed to be uniform alongside the heater in a first approximation to avoid dispensable fitting constants.

During FDNB, the energy stored in the mantle results from the competition between the heat input supplied from the wall and the cooling processes due to forced convection (that will be detailed in section 4.3). Because of the exponential nature of the heat input, the energy density rises in time. Once it reaches the critical value, *i.e.* when the local subcooling becomes null, bubbles generated at the wall can no longer condense. They coalesce triggering the formation of irreversible vapor pockets, which next results in a boiling crisis.

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The model describes the exchanges between two homogeneous zones presented in Figure 2:

- The mantle of thickness δ , where the energy density is homogenized by the NCCs. This thickness is assumed to be small compared to the channel width.
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• The bulk, where cold liquid water flows at a high Reynolds number and high subcooling. The bulk temperature is considered as being unmodified during the transient heating process.

The energy density homogeneity in the mantle is a reasonable approximation. Indeed, during FDNB, the high speed videos revealed the small size of the bubbles, around 100 μm , which is two orders of magnitude smaller than the width of the channel. Therefore, we expect the mantle thickness to have the order of magnitude of the bubble diameter and small compared to the channel width. By their pulsating behavior, the generated bubbles would then mix the fluid in mantle and homogenize its temperature. Besides, the energy density is considered to be constant in the direction of the width of the heater.

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This model relies on some input data which are experimental quantities : *i*) thermal and hydraulic operating conditions (pressure, subcooling, mass flow rate, time period for the exponential rise), *ii*) the measured space-averaged heat flux transferred to the water $q''_w(t)$.

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This approach is akin to the model of Weisman and Pei [29] who proposed an interaction between 295 two distinct domains due to turbulent velocity fluctuations. However, Weisman and Pei considered 296 the exchange of bubbles whereas our model proposes to study an exchange of energy. Moreover, 297 our model is also akin to the critical enthalpy approach proposed by Tong [30] who conducted an 298 enthalpy balance in the close vicinity of the wall and proposed a criterion on the enthalpy value. 299 However, the lack of physical modeling of the various terms of the enthalpy balance and the stated 300 critical enthalpy led Tong to use numerous correlations on experimental data. Moreover, these two 301 approaches [30, 29] were developed to investigate steady heating situations. The literature has widely 302 reported (e.g. [7, 8, 9]) that when the power escalation period is small enough, the value of CHF 303 differs from its value for longer period and depends on the power escalation period, bringing to 304 light transient effects. Failing to predict whether a case can be considered as quasi steady-state or 305 period-dependent, it is then necessary to develop a model considering a time-dependent mechanism 306 to describe the transient boiling crisis. 307

308 3 Mathematical formulation

309 3.1 Criterion for the Boiling Crisis

As stated above, the criterion associated with the triggering of boiling crisis under the considered conditions is when energetically, an elementary volume of liquid water (dV) in the mantle is heated from the initial subcooled temperature to saturation, corresponding to an energy rise of $c_p \rho_l \Delta T_{sub} dV$. The critical energy density rise $E_{cr}^{''}$ will then be defined by:

$$E_{cr}^{\prime\prime\prime} = \rho_l \, c_p \, \Delta T_{sub} \tag{1}$$

³¹⁴ When the local energy density rise in the mantle reaches this critical value $E_{cr}^{'''}$, the next generation ³¹⁵ of bubbles will no longer condense. These bubbles will instead laterally merge triggering the boiling ³¹⁶ crisis. The critical energy density rise $E_{cr}^{'''}$ is thus a suitable criterion to characterize the boiling crisis.

It is worth to note that this criterion does not involve directly the latent heat. We have shown 318 that under conditions of interest, bubbles have a short lifetime: less than $100 \,\mu s$. This is 2 to 5 orders 319 of magnitude smaller than the period of the exponential power excursion which is the characteristic 320 time scale of the investigated phenomenon. As stated in section 2.2, the model assumes that the 321 energy required to generate a bubble, *i.e.* involving the latent heat, is then entirely released to the 322 adjacent liquid in the mantle, *i.e.* converted to sensible heat. In other words, the contribution of 323 the latent heat is mechanistically considered as an intermediate step which efficiently transfers the 324 heat from the wall to the liquid phase. This temporary process has a time scale much smaller than 325 the time scale of the investigated phenomenon, *i.e.* the power escalation period τ . Therefore, it is 326 reasonable not to include the latent heat in this criterion for the proposed model. 327

328

In the following, we aim to establish an equation on the local energy density rise describing its evolution during the transient heating.

331 3.2 Governing equations of the mantle

To describe mathematically the evolution of the local energy density, one needs to establish an energy balance in the mantle. Let us consider the mantle region of thickness δ which separates the wall from the bulk fluid as depicted in Figure 3. The assumptions discussed in section 2.2 consider that the

physical quantities do not depend on the variable z. The successive nucleation-condensation cycles 335 of the bubbles induce homogenization in the transverse direction y inside the mantle. The heat flux 336 $q_w^{\prime\prime}(t)$ supplied from the wall to the fluid contributes to the bubble generation. The energy of the 337 fluid in the mantle increases gradually due to heat released by NCCs. Conversely, part of this energy 338 is lost due to two contributions. The first one is the advection in the streamwise direction due to 339 the vertical velocity component (u_m in Figure 3). The second one is the heat exchange between the 340 mantle and the bulk due to turbulent velocity fluctuations (v_m in Figure 3). These exchanges will 341 be discussed in section 3.3. 342

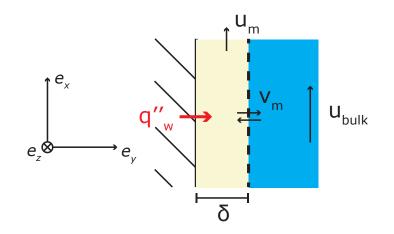


Figure 3: Schematic description of the mantle $(y \in [0, \delta])$

An elementary control volume $\sigma(x)$ is defined as an element of volume $dx \ \delta \ dz$ at the vicinity of the wall, between x and x + dx. In the y-direction, the length of the elementary volume is δ because we consider the entire mantle thickness. This definition is illustrated in Figure 4.

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Figure 4: Description of the entire system considering the total length L of the heater and the exchanges of the elementary system $\sigma(x)$ used for the energy balance.

The considered system $\sigma(x)$ has a total energy $E_{\sigma}(x,t)$ [J] carried by the fluid within it. By considering the bulk energy density $E_0^{\prime\prime\prime}$ [J.m⁻³] and the energy density rise $E^{\prime\prime\prime}(x,t)$ [J.m⁻³], one can define:

$$E_{\sigma}(x,t) = \left(E^{\prime\prime\prime}(x,t) + E_0^{\prime\prime\prime}\right) \, dx \, \delta \, dz \tag{2}$$

The variation of energy dE_{σ} is written:

$$dE_{\sigma} = E_{\sigma}(x, t + dt) - E_{\sigma}(x, t)$$
$$= (E'''(x, t + dt) - E'''(x, t)) dx \,\delta dz$$

351 thus

$$dE_{\sigma} = \frac{\partial E^{\prime\prime\prime}}{\partial t} \, dx \, \delta \, dz \, dt \tag{3}$$

³⁵² The exchange of energy at the interface is written:

$$dE_{\sigma} = \delta Q_w - \delta Q_{x+}^{\sigma(x)} + \delta Q_{x-}^{\sigma(x)} - \delta Q_b^{\sigma(x)}$$
(4)

³⁵³ where (see Figure 4):

- δQ_w is the heat coming from the wall.
- $\delta Q_{x-}^{\sigma(x)}$ is the heat coming by advection from $\sigma(x-dx)$.
- $\delta Q_{x+}^{\sigma(x)}$ is the heat leaving the control volume by advection to $\sigma(x+dx)$.
- $\delta Q_b^{\sigma(x)}$ is the heat transferred at the interface mantle-bulk (at a distance $y = \delta$ from the wall). the expressions of the different terms are:

 $\delta Q_w = q''_w(t) \, dx \, dz \, dt \tag{5}$

$$\delta Q_{x-}^{\sigma(x)} = u_m (E_0^{'''} + E^{'''}(x,t)) \,\delta \,dz \,dt \tag{6}$$

$$\delta Q_{x+}^{\sigma(x)} = u_m (E_0^{'''} + E^{'''}(x + dx, t)) \,\delta \,dz \,dt \tag{7}$$

$$\delta Q_b^{\sigma(x)} = q_b''(x,t) \, dx \, dz \, dt = v_m \, E^{'''}(x,t) \, dx \, dz \, dt \tag{8}$$

with $q_b''(x,t) = v_m E'''(x,t)$ the net heat flux transferred at the interface mantle-bulk. The demonstration of its expression will be presented in section 3.3. These expressions substituted in equation 4 give after simplification:

$$\frac{\partial E^{'''}}{\partial t} + u_m \frac{\partial E^{'''}}{\partial x} + \frac{v_m}{\delta} E^{'''} = \frac{q_w^{''}}{\delta} \tag{9}$$

In the present situation with an established forced convection and with high heat fluxes supplied from the wall, the following terms may be neglected: kinetic, gravitational, viscous dissipation and pressure effects.

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Equation (9) can be transformed into a non-dimensional expression. The dimensionless volumetric energy density rise E^* is defined with respect to the critical energy: $E^* = E'''/E''_{cr}$. The length of the heater, L, is used to set a normalized form of the variable x: $x^* = x/L$. Time period τ of the exponential rise is used to define a normalized time: $t^* = t/\tau$. Substituting these three quantities in Eq. 9, we obtain:

$$\frac{\partial E^*}{\partial t^*} + N_x \frac{\partial E^*}{\partial x^*} + N_y E^* = \frac{\tau}{E_{cr}^{\prime\prime\prime}\delta} q_w^{"}$$
(10)

where N_x and N_y are two non-dimensional groups defined as:

$$N_x = \frac{u_m \tau}{L} \qquad N_y = \frac{v_m \tau}{\delta} \tag{11}$$

A well posed mathematical problem requires for this first-order partial differential equation to have initial and boundary conditions. At time $t^* = 0$, the temperature of the fluid is uniform in the whole channel, equals to the inlet temperature : $E^*(x^*, 0) = 0$. The fluid entering the heated section, at $t^* = 0$, has a temperature equal to the bulk temperature which remains the same during the whole transient heating process. This condition reads $E^*(0, t) = 0$, $\forall t > 0$. To fully formulate the mathematical problem, we still need to define the two velocities u_m and v_m characterizing the ³⁷⁸ cooling process induced by the forced flow.

³⁷⁹ **3.3** Heat transport induced by the flow

The velocity in the streamwise direction is $u(\vec{x},t) = U(y) + u'(\vec{x},t)$. Neglecting the fluctuating component $u'(\vec{x},t)$, this velocity will be approximated by its mean component U(y), this latter being given by the law of the wall for a turbulent channel flow. As strong velocity gradients are present near the wall, a spatial average along the mantle thickness will also be considered:

$$u_m(\delta) = \frac{1}{\delta} \int_0^\delta U(y) \, dy \tag{12}$$

Once the bubbles are generated at the wall, the mean velocity profile is perturbed from the law of the wall. Nonetheless, its use as a first approximation to compute u_m is reasonable. The latter is a space averaged velocity within the thickness δ which is greater than the diameter of the bubbles, implying that most of the area accounted for to compute the mean velocity is sparsely influenced by the bubbles.

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Moreover, as described above, the bubbles are small, quasi-spherical and pulsate at high frequency 390 without having time to slip over the surface. This leads to think that these flow perturbations do not 391 influence the streamwise average flow as the growth and collapse would be achieved symmetrically 392 compared to the center of a bubble and as the period of the pulsation is small compared to the char-393 acteristic time period of the experiment (τ) . This growth and collapse behavior however influences 394 the instantaneous flow contributing to the mantle mixing. Finally, bubbles are confined in close 395 vicinity of the wall where the velocity is strongly reduced due to the viscosity of water. Therefore, 396 most of the weight U taken into account by the calculation of the mean velocity u_m is taken where 397 the fluid is in single-phase liquid. 398

399

Then, one has to describe the heat exchange between the mantle and the bulk due to turbulence in the y direction. The advection at the interface by the turbulent velocity fluctuations is taken into account by a characteristic velocity v_m . Let us first recall the usual definitions for the quantities used in the description of turbulent flows.

 $_{404}$ - u^* is the wall shear velocity calculated with the friction factor, using Blasius (Re < 30,000) and $_{405}$ McAdams (Re > 30,000) correlations as suggested in [31] (see chapter 9, section I-C (p.379)), 406 - $\delta_{\nu} = \nu/u^*$ is the viscous sublayer unit, with ν the kinematic viscosity of water.

407 - $Re_{\tau} = u^* e / \nu$ is the wall Reynolds number where e is the channel half width.

The corresponding values of these quantities under the investigated conditions are presented in Table 1. Hereafter, we will use the following definitions: $U^+ = U/u^*$ for the dimensionless velocity and $Y^+ = y/\delta_{\nu}$ for the normalized distance to the wall.

Re [-]	$\Delta T_{sub} \left[K \right]$	$Re_{\tau}\left[- ight]$	$\delta_{\nu} \left[\mu m \right]$	$u^* \left[cm.s^{-1} \right]$	
8500	50	182	28	2.0	
13500	25	272	18	2.1	
	25	467	67 11	3.6	
25000	50			5.2	
	75				8.4
	25	622	622	8.0	4.8
35000	50				6.9
	75				11

412

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Table 1: Turbulent flow characteristics for the considered conditions of [9] and for the present channel geometry. $Re = \frac{GD_h}{\mu}$ with G the mass flux, D_h the hydraulic diameter and μ the dynamic viscosity.

As featured in section 3.2, the heat exchanges between the mantle and the bulk are due to the transverse turbulent velocity fluctuations. Let us consider a given transverse turbulent velocity fluctuation v', the elementary transfer of heat at the mantle-bulk interface dq''_b is given by :

$$dq_b''(v') = \begin{cases} E_0''' v' P(v') dv' & \forall v' < 0\\ (E_0''' + E''') v' P(v') dv' & \forall v' > 0 \end{cases}$$
(13)

where P(v') is the probability density function (PDF) of the transverse velocity component v'. As illustrated in Figure 5, the first line describes a transport of cold bulk water towards the mantle and the second one describes the heated water leaving the mantle to the bulk. In order to have the net heat transport, all the possible velocity fluctuations weighted with their probability must be taken into account. This results to the following integral:

$$q_b'' = \int_{-\infty}^{+\infty} dq_b''(v')$$
 (14)

$$= \int_{-\infty}^{0} E_0^{'''} v' P(v') \, dv' + \int_{0}^{+\infty} (E_0^{'''} + E^{'''}) \, v' P(v') \, dv'$$
(15)

$$= E_0^{\prime\prime\prime} \int_{-\infty}^0 v' P(v') \, dv' + (E_0^{\prime\prime\prime} + E^{\prime\prime\prime}) \int_0^{+\infty} v' P(v') \, dv'$$
(16)

$$= E_0^{\prime\prime\prime} \int_{-\infty}^{+\infty} v' P(v') \, dv' + E^{\prime\prime\prime} \int_0^{+\infty} v' P(v') \, dv'$$
(17)

 $_{417}$ v' being a turbulent velocity fluctuation,

$$\int_{-\infty}^{+\infty} v' P(v') dv' = \langle v' \rangle = 0$$
(18)

the first term of equation 17 is then null and the net heat flux at the interface mantle-bulk is given by $q_b'' = v_m E'''$ with:

$$v_m = \int_0^{+\infty} v' P(v') \, dv' \tag{19}$$

With v_m the characteristic velocity of the transverse turbulent velocity fluctuation. This characteristic velocity is also the expected value of the positive velocity fluctuation: $v_m = \mathbb{E}(v' \mid \mathbb{R}^+)$. Besides, decomposing v_m enables a better understanding of its two contributions: the cold bulk water inflow and the warmed water outflow. Indeed, as $\langle v' \rangle = 0$, $\int_{-\infty}^{0} v' P(v') dv' = -\int_{0}^{+\infty} v' P(v') dv' = -v_m$ and one can rewrite equation 16 as:

$$q_b'' = \underbrace{v_m(E_0^{'''} + E^{'''})}_{\text{Cold bulk water inflow}} - \underbrace{v_m E_0^{'''}}_{\text{Cold bulk water inflow}}$$
(20)

which is illustrated in Figure 5. Noteworthy, we model the heat exchange in the normal direction by an interaction between two homogeneous media in term of temperature, the mantle and the bulk. Consequently, this choice of modeling does not involve thermal turbulent fluctuations terms such as $\langle v'T' \rangle$.

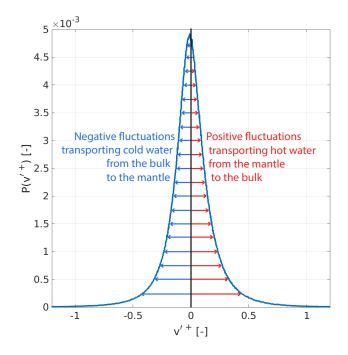


Figure 5: Schematic description of the velocity fluctuation contributions at the interface mantle-bulk. The PDF is extracted from the data of [32] with $Re_{\tau} = 1000$ at $y^+ = 10$. Noteworthy, the asymmetry reflects the anisotropy of the near-wall flow, while the property $\langle v'^+ \rangle = 0$ remains verified.

The formulation of the characteristic velocity v_m is akin to the characteristic velocity defined by 429 Weisman & Pei [29] and Pasamehmetoglu [20]. In their case, they aim to determine the velocity of 430 liquid inflowing a layer (the bubbly layer for Weisman and Pei and the macrolayer for Pasamehme-431 toglu) at low subcooling where vapor effectively leaves the denominated zone, characterized by a 432 vapor ejection velocity. In our case, bubbles do not depart from the wall because of the high sub-433 cooling. Thus, at a distance greater than the bubble diameter, in particular at a distance δ from 434 the wall, there is no vapor mass flux escaping. Moreover, bubbles have a pulsating behavior. In 435 our model, we chose to assume that the velocity field generated by the bubble growth is dampened 436 by the bubble collapse and that these velocities have no significant influence on the exchanges at 437 the interface mantle-bulk. For these reasons, a null vapor ejection velocity appears to be a quite 438 reasonable approximation in our case and thus our proposed expression of v_m does not contradict 439 theirs. However, the present expression establishment and its use in Equation 10 takes into account 440 the whole distribution of the transverse turbulent velocity fluctuations, and not only a part as in 441 [29] and [20], improving the use of this physical quantity. Plus, these authors make use of assumed 442 expressions of the PDF P(v'), Gaussian for Weisman and Pei and Hyperbolic for Pasamehmetoglu, 443 whose accuracy is not quantitatively assessed. 444

445

In order to compute v_m , one needs to know of P(v'). This latter function can be obtained by

analyzing Direct Numerical Simulation (DNS) data or by making analytic assumptions on the function P(v'). In the present paper, we choose to use DNS data as discussed shortly hereafter. DNS simulations were performed by Moser et al. [33] and Graham et al. [32] to study turbulent flows inside a rectangular channel. We use the latter to compute the value of v_m as a function of different value of Re_{τ} which enables interpolations to each specific experimental conditions. The detail of the process is developed in the appendix A.

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In their calculation, Weisman and Pei assumed that P(v') has a Gaussian distribution every-454 where in the domain. Pasamehmetoglu assumed a hyperbolic distribution, $P(v^{'}) \propto (1/v^{'})^{n}$ with 455 n, an adjustable empirical coefficient equal to 4. However, this choice seems to be the result of an 456 empirical fitting. On the other side, assuming a Gaussian distribution could be relevant in the bulk. 457 However, this is no longer true near the wall as anisotropy deviates the probability density function 458 from a Gaussian distribution. This analysis, detailed in Appendix A, is illustrated in Figure 6b where 459 we plot the relative discrepancy between each resulting v_m^+ , between our methodology and the one 460 proposed by Weisman & Pei. For our working conditions, *i.e.* with a Reynolds number up to about 461 600 (see Table 1), the difference can be as high as 16 % for the near-wall flows. However, the error 462 can be as high as 50% difference when the wall Reynolds number reaches higher values relevant for 463 extended applications. Based on this analysis, we decided to use directly PDFs obtained by DNS 464 simulations to compute v_m . 465

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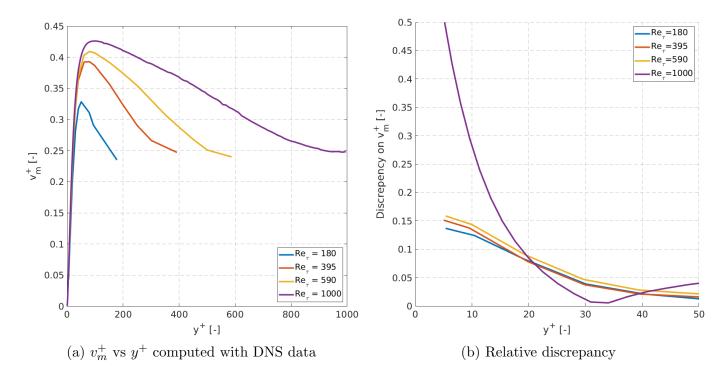


Figure 6: Dimensionless velocity v_m^+ as a function of the dimensionless normal coordinate y^+ calculated for $Re_{\tau} = 180, 395, 590, 1000$ with DNS data of Moser et al. [33] and Graham et al. [32]. Relative discrepancies between the calculation of v_m^+ using PDF data and the Gaussian distribution assumption are presented.

The current calculation of v_m uses single-phase DNS data. In fact, the growth and collapse of bubbles at the wall induces supplementary turbulent velocity fluctuations. Particularly, they would most likely increase the value of v_m : the growth adding positive fluctuations and the collapse negative ones, v_m defined as the integration of the fluctuation in a direction would necessarily increase. However, quantifying the influence of the bubble-induced fluctuations is currently out of range. Consequently, in the present model, we assume that the fluctuations induced by the bubbles do not impact the velocity v_m .

474 3.4 Model Implementation and Output

⁴⁷⁵ We will now discuss the various parameters involved in Equation 9:

• $q''_w(t)$ is the heat flux released from the wall to the fluid. This time-function is known from experimental data. In all experiments the heat flux distribution on the boiling surface was spatially uniform until the boiling crisis. Therefore, a space-averaged value of heat flux is used as an input to our model.

• the characteristic velocities u_m and v_m have been presented in section 3.3. Both quantities depend on the operating conditions (pressure, bulk temperature, mass flow rate) and also on 482

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the mantle thickness δ .

• The mantle thickness δ is a priori unknown.

The present model assumes that boiling crisis happens when the condition $E'''(x, t_{CHF}) = E_{cr}'''$ is reached. It is used to estimate the *a priori* unknown quantity δ .

In order to assess the thickness δ , a guess-estimate approach is realized as described in the 487 following and illustrated in the flowchart in Figure 7. To do so, we use the time-dependent infrared 488 thermography information recorded for the experimental CHF investigation of Kossolapov et al. [9]. 489 Particularly, for each test, we extracted two quantities and used them as input in the algorithm: 490 the time of the boiling crisis t_{CHF} , and the recorded space-averaged heat flux $q''_w(t)$ (time t ranging 491 between zero and t_{CHF}). A first value of δ is chosen and Eq.(10) is then integrated with an explicit 492 forward Euler method from t = 0 to $t = t_{CHF}$. If the volumetric energy density rise at time t_{CHF} 493 differs from the critical value, the δ value is considered wrong. Another value is fixed and the process 494 is repeated again. The correct value δ is obtained when convergence is achieved: 495

$$|\max_{x^* \in [0,1]} (E^*(x^*, t^*_{CHF})) - 1| < \varepsilon$$
(21)

with ε , the criterion of convergence. As in this investigation, the heat flux input is uniform along the *x*-direction, E^* is a monotonically increasing function in the streamwise direction and the maximum is then located at the extremity, downstream the heating wall, *i.e.* at $x^* = 1$. Plus a criterion of convergence of 10^{-3} has been selected on our case.

It is worth to note that this quantity δ is the result of this algorithm and not the outcome of a measurement. The measurement of such a quantity is currently not possible. Indeed, one would need to quantitatively and finely measure the temperature field close to the heating wall. However, due to the thin mantle thicknesses involved, the turbulent thermal flow and the numerous bubbles located at the wall, this measurement is currently impossible.

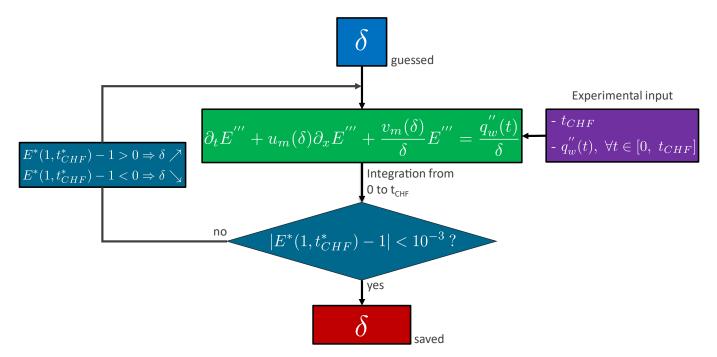


Figure 7: Schematic description of the guess-estimate algorithm allowing for the determination of the mantle thickness δ for a given experimental run.

⁵⁰⁵ 4 Results and physical discussion

506 4.1 Evaluation of the mantle thickness

507 4.1.1 Experimental results and correlation

Equation (10) is solved for the considered set of experimental conditions. The obtained values for the thickness δ are plotted as a function of the time period τ in Figure 8a. The values can also be normalized using the length $\delta_{\nu} = \nu/u^*$ which is the relevant turbulent length scale in the transverse direction (Figure 8b):

$$\delta^+ = \frac{\delta}{\delta_\nu}$$

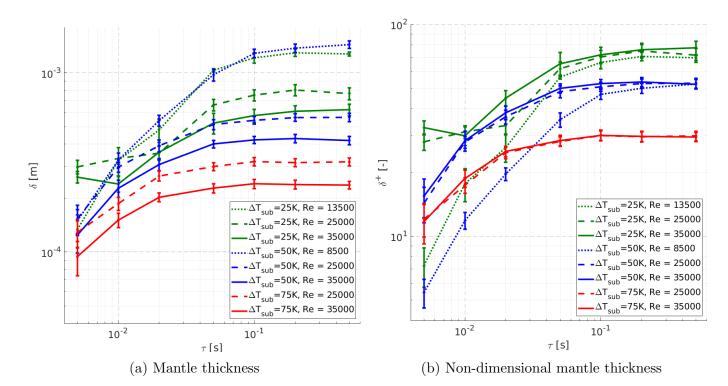


Figure 8: Thickness of the mantle δ [m] and its dimensionless form δ^+ [-] as a function of the excursion period τ [s] for the eight operating conditions.

Each of the eight curves plotted in Figure 8 consists in seven points (5, 10, 20, 50, 100, 200, 500 ms). For each point, three runs were conducted. Therefore, the results presented in Figure 8 are derived from 168 measurement points. The considerations to compute the uncertainty on δ are detailed in appendix B.

512

The mantle thickness is presented in Figure 8a. It goes from 100 μm for the short periods and 513 high Reynolds numbers to 2 mm for long periods and low Reynolds numbers. For the high subcool-514 ing degrees (50 K and 75 K), these values are slightly larger (short periods) or significantly larger 515 (long periods) than the bubble diameters, *i.e.* that supports the assumption presented in section 3.3. 516 However, for 25 K of subcooling, the mantle thickness takes values smaller than the bubble diameters 517 (discussed in section 4.1.2). One can note that δ increases with the period τ until a plateau which 518 is reached for τ larger than 100 ms. This increasing trend is regular for most of the test, except 519 for the ones with $\Delta T_{sub} = 25K$. The value taken by this plateau decreases with the increase of the 520 subcooling and the Reynolds number, but no quantitative regularity is observed. However, when 521 the mantle thickness is normalized by the length δ_{ν} (Figure 8b), the value taken at the plateau only 522 depends on the subcooling showing three clear limit values. 523

524

These observations lead to propose a new normalization on the mantle thickness and on the

power escalation period. The mantle thickness is qualitatively related to the thermal boundary layer. In order to account for both turbulent dynamic boundary layer and thermal boundary layer, a relevant approach is to define a normalization quantity as $\delta_T = \delta_{\nu}/Pr = \alpha/u^*$, with Pr and α being respectively the Prandtl number and the thermal diffusivity of water at the considered inlet conditions. Therefore we define the non-dimensional mantle thickness δ^{++} as

$$\delta^{++} = \frac{\delta}{\delta_T}$$

To normalize the power escalation period, we choose to use the time scale linked with the advection in the mantle, *i.e.* in the streamwise direction, as it corresponds to the major velocity component. Moreover, as each curve $\delta(\tau)$ converges towards an upper limit (plateau) associated with steady-state conditions, it seems worth to use this time scale at steady-state in order to assess the transient nature of the escalation process. Therefore, we define τ_x as

$$\tau_x = \frac{L}{u_{m,\infty}} \tag{22}$$

with $u_{m,\infty}$ the value taken by u_m in steady-state. This time scale only depends on the steady-state quantities and can be obtain analytically. Here "steady-state" is in fact a quasi steady-state and corresponds to the asymptotic behavior observed for large values of the power escalation period τ . This is characterized by a quantity, *e.g.* δ in Figure 8 or the CHF value in Figure 5 in [9], which does not depend on the power escalation period. When τ approaches infinity, Eq.(10) is reduced to the following equation:

$$\frac{dE_{ss}^{*}(x^{*})}{dx^{*}} + \frac{v_{m,\infty}L}{u_{m,\infty}\delta_{\infty}}E_{ss}^{*}(x^{*}) = \frac{L}{\delta_{\infty}}\frac{q_{ss}^{''}}{u_{m,\infty}E_{cr}^{'''}}$$

where the subscripts "ss" and " ∞ " stand for steady-state conditions. This differential equation is solved using the boundary condition $E_{ss}^*(0) = 0$:

$$E_{ss}^*(x^*) = \frac{q_{ss}^{''}}{E_{cr}^{'''} v_{m,\infty}} \left(1 - e^{-x^*/\lambda}\right) \qquad \text{with} \qquad \lambda = \frac{u_{m,\infty} \,\delta_\infty}{v_{m,\infty} \,L} \tag{23}$$

As $E_{ss}^*(x^*)$ is a increasing function on x^* , the maximum volumetric energy density is observed downstream of the heater, *i.e.* $x^* = 1$. Setting $E_{ss}^*(1) = 1$, we obtain the following relation:

$$\frac{1 - e^{-1/\lambda}}{v_{m,\infty}} = \frac{E_{cr}^{'''}}{q_{ss}^{''}} \tag{24}$$

Beyond the thermal hydraulics conditions, the left-hand-side term only depends on δ_{∞} and the righthand-side one only depends on the CHF value at steady-state. The value of τ_x can thus be determined knowing CHF at steady-state.

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⁵⁴⁴ The experimental points are then plotted in Figure 9 using normalized quantities on both axis:

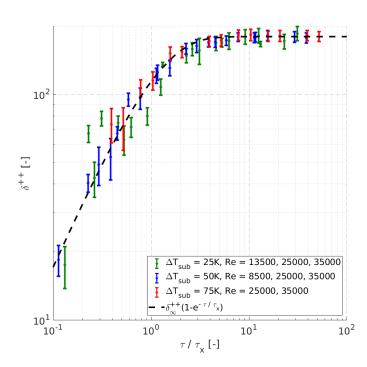


Figure 9: Non-dimensional thickness δ^{++} [-] as a function of the normalized period τ/τ_x [-] for the eight operating conditions ($\Delta T_{sub}, Re$), represented by the error bars. The fitting function (dashed line) corresponds to $\delta_{\infty}^{++} = 180$.

545 It shows that all available data sets are satisfactorily fitted by the following equation:

$$\delta^{++}(\tau) = \delta^{++}_{\infty} \left(1 - e^{-\tau/\tau_x} \right)$$
(25)

where δ_{∞}^{++} is the only tuning parameter and corresponds to the normalized mantle thickness in steady-state conditions. A single value, equals to 180 in the present case, is suitable for all operating conditions.

549 4.1.2 Discussion

Results presented in Figure 9 show that the quality of the fit between the experimental results and equation (25) depends on the subcooling. For high subcoolings (50 K and 75 K), the fit is excellent.

Indeed, more than 75 % of these points are predicted with \pm 5 % error. However, some tests, as-552 sociated with short periods $(\tau/\tau_x < 1)$ and a small subcooling (25 K) present some discrepancies. 553 The latter may be explained, supporting the veracity of the our mechanistic assuptions. Indeed, to 554 be valid, the present model needs a sufficient degree of subcooling so that nucleation-condensation 555 cycles (NCCs) presented in section 2.2 can take place. However, for a relatively small subcooling 556 such as 25 K and especially for short periods, the major assumption of the model can reach its limit. 557 Due to the subcooling, bubbles grow large and have a longer lifetime, about a few milliseconds. It 558 implies that the duration of a growth and collapse cycle may no longer be negligible in front of the 559 power escalation period and consequently, the mixing induced by NCCs may be not efficient enough 560 to make the mantle homogeneous. This explains the excellent fit for all the points, but also the 561 discrepancies for the points with relatively low subcooling (25 K) and fast transient ($\tau/\tau_x < 1$). 562

563

Equation (25) proposes a simple relation between the mantle thickness δ through its non-dimensional 564 form δ^{++} and the different working parameters. This shows that the model is able to accurately 565 handle the different working parameters. Equation (25) includes a unique non a priori calculable 566 constant δ_{∞}^{++} which corresponds to the value taken by the normalized mantle thickness at steady-567 state for all the conditions of this set. The fit with the experimental data gives δ_{∞}^{++} equals 180 for 568 the current set of conditions. However, this quantity is expected to depend on other parameters such 569 as the pressure or the quantity λ defined in Equation (23). The quantity λ represents the ratio at 570 steady-state between heat removal in the x and the y directions. It linearly depends on the heated 571 length L. For the current set of experimental conditions, λ takes values close to unity or above, 572 meaning that heat removal in the x direction prevails or is equivalent to that in the y direction. If 573 considering cases where the heat removal in the y direction significantly prevails, one would expect 574 the constant δ_{∞}^{++} to decrease since in this case heat transfer involves the whole length of the heater. 575 576

The present model relies on an energy balance in the fluid and does not take into account the surface condition of the heater. Nonetheless, it is known that boiling phenomena, including boiling crisis, depend on key parameters which are surface conditions: nucleation site density, roughness, wettability, porosity. In our experiments, the exponential electrical heat input is released either in the substrate or to the water. The proportion in time of each part is determined by the effusivity of both media (water and sapphire) and by the surface conditions once the boiling occurs. Therefore, our approach implicitly takes into account the surface conditions as well as the thermal inertia of the ⁵⁸⁴ substrate via the time function $q''_w(t)$, defined as the net heat flux released to the water. Moreover, at ⁵⁸⁵ such a high degree of subcooling, bubbles present a high-frequency pulsating behavior which establish ⁵⁸⁶ NCCs, mixing the fluid in the mantle. It is then reasonable to assume that the major phenomenon ⁵⁸⁷ leading to boiling crisis is the transient heating process in the mantle as described in equation (9). ⁵⁸⁸ This would certainly not be the case for lower subcooling.

589

Mechanistically speaking, the usability range of the model is related to the occurrence of the assumed mechanisms: *i.e.* the homogenization of the mantle temperature throughout the action of the NCCs and the cooling processes characterized by the velocities u_m and v_m .

For instance, in case of pool boiling, the velocity v_m , based on turbulent velocity fluctuations, is not 593 even defined. Moreover, in such a case, the definition and the existence of a homogeneous mantle is 594 questionable as the physical mechanism governing the wall-vicinity cooling is significantly different. 595 Besides, in case of really short transients ($\tau < 5 ms$), all nucleation sites may be activated simulta-596 neously on the wall. Therefore, as observed by Kossolapov et al. [9], the boiling crisis can directly 597 be triggered at ONB by coalescence of the first generation of bubbles. Furthermore, even if some 598 generations of bubbles occur, the time spent in nucleate boiling regime may be too short to let the 590 NCCs sufficiently homogenize the mantle. Moreover, the lifespan of a bubble (about 0.05 ms) may 600 become non-negligible compared to the power escalation period if the latter becomes too small, going 601 against one of the modeling assumptions. 602

Conversely, at a pressure higher than the atmospheric one, the model might still be usable. Indeed, a slight increase of the pressure would decrease the bubble size and thus the mantle thickness, NCCs should still occur and homogenize the mantle. However, if the pressure rises too much beyond the atmospheric pressure, *i.e.* beyond a few tens of bars, bubbles might be too small to let the NCCs to happen. Indeed, bubbles may for example not grow enough to go beyond the superheated layer, and thus cannot re-condense.

Finally, some computation assumptions must be discussed. In a first hand, as presented in section 3.3, v_m is computed using single-phase DNS data of turbulent velocity fluctuations whereas the latter is most likely increased by the bubble growth and collapse. However, the quantification of this increase is currently out of range. In a second hand, the same equation is used during the entire transient whereas during the single-phase regime, there is no NCC and thus the mantle does not have a physical meaning. During this regime, the energy is not homogenized as there is no

⁶⁰⁹

NCC and is mostly confined in the conductive thermal boundary layer. For a given condition, this 616 conductive boundary layer is much smaller than the associated mantle thickness. For instance, at 75 617 K of subcooling and a period of 5 ms, the conductive layer is about 30 μm thick (~ $\sqrt{\alpha \tau}$) whereas 618 the mantle is 100 μm thick (see Figure 8a). Consequently, the energy released in the liquid is more 619 restrained close to the wall where the flow is not as efficient too dissipate the energy. Therefore, 620 during the single-phase regime, the model in fact uses dissipation processes more efficient than it 621 should be. Nonetheless, this discrepancy is strongly attenuated as during the single-phase regime, 622 the energy released in the liquid is low and so the energy in the mantle, implying that the energy 623 dissipated by the model is also low (being a function of E''). In order to ensure that this dissipation 624 discrepancy is low, we realized a sensibility test where during the single-phase regime, no dissipation 625 is computed and all the energy remains in the mantle in order to consider the limit case. The 626 calculation shows that the mantle thickness almost does not vary, the discrepancy being only a few 627 percents, supporting the fact that using the dissipation terms of the model during the entire transient 628 does not significantly impact the results. 629

⁶³⁰ 4.2 Energy distribution along the heated wall

Solving the energy balance (Equation (10)) allows one to access the function $E^*(x^*, t^*)$. The volumetric energy density rise is plotted in Figure 10 as a function of the distance x^* , at time $t^* = t^*_{CHF}$ corresponding to the time of boiling crisis. Results are presented for two conditions of subcooling, 50 K (Figure 10a) and 75 K (Figure 10b). Both cases include seven values of the time-period τ and the analytic solution for steady-state condition (Equation (23)).

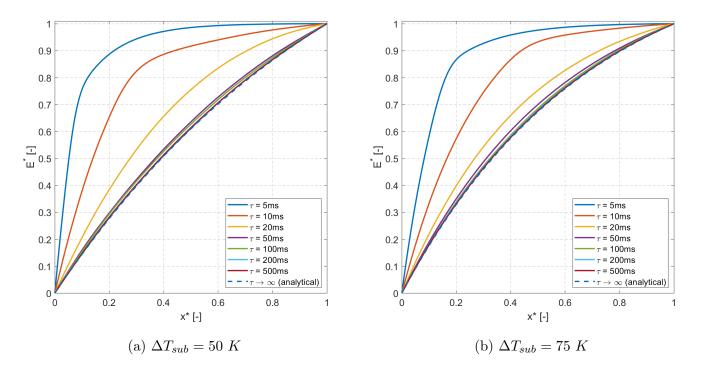


Figure 10: $E^*(x^*, t_{chf}^*)$ [-] for 50 K and 75 K of subcooling, for Reynolds number of 35000 and a time-period ranging within 5 ms to 500 ms. The analytic solution corresponds to the steady-state case, given by Equation (23).

Figure 10 shows that the set of curves is very similar at 50 K and 75 K. This result confirms 636 the relevance of the dimensionless approach. The volumetric energy density rise is seen to increase 637 with the coordinate x^* . As expected, boiling crisis is more likely to happen downstream the heated 638 plate for long time-periods, greater than 20 ms, as a regular increase of E^* with x^* is noticeable in 639 both Figures. About 20 percent of the plate length $(0.8 < x^* < 1)$ is associated with a volumetric 640 energy density in the mantle greater than 90% of the critical energy. One will also note that curves 641 with a time period longer than 50 ms almost overlap, nearly matching the analytic solution derived 642 for an infinite time-period. A different behavior should be observed for very fast transients. The 643 curves presented in Figure 10 for the shortest time-periods, *i.e.* 5 ms and 10 ms, reveal a different 644 increase of the volumetric energy density rise with x^* . For $\tau = 10$ ms, more than 50 percent of the 645 plate length $(0.5 < x^* < 1)$ has a volumetric energy density in the mantle greater than 90% of the 646 critical energy. This ratio increases up to 80% for $\tau = 5$ ms. One expects therefore a large dry 647 spot to occur and to cover most of the plate. The existence of these two regimes of boiling crisis is 648 confirmed experimentally. A link with the two non dimensional groups N_x and N_y will be shown in 649 the following section. 650

4.3 Impact of the non dimensional groups N_x and N_y on boiling crisis

⁶⁵² The energy balance equation (10) includes two non dimensional groups defined as:

$$N_x = \frac{u_m \tau}{L} \qquad N_y = \frac{v_m \tau}{\delta}$$

These quantities are intrinsically connected with the mantle thickness δ as they involve the characteristic velocities u_m and v_m . The iterative solving procedure of Equation (9) yields a single couple (N_x, N_y) for each experimental run. These quantities are plotted as a function of the time period τ in Figure 11.

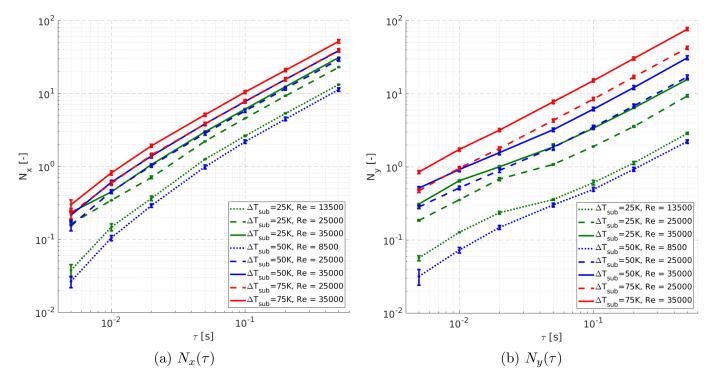


Figure 11: Dimensionless groups N_x and N_y [-] versus the excursion period $\tau[s]$

⁶⁵⁷ 4.3.1 Physical meaning of N_x

The group N_x is the ratio of two characteristic times: τ which is the power excursion period, and L/u_m which is the time needed for a fluid particle to travel in the mantle from the inlet (x = 0 *i.e.* $x^* = 0$) to the outlet section (x = L *i.e.* $x^* = 1$).

Value of N_x smaller than unity means that the fluid particle is "trapped" in the heated mantle during the period τ . As a result, the temperature of the mantle increases. In contrast, N_x greater than unity means that the fluid particle has enough time to be advected alongside the heated area during a time period τ . The temperature of the mantle is slightly modified. From the mathematical point of view, the group N_x represents the magnitude of the spatial variations in the flow direction. ⁶⁶⁶ No energy gradient should be observed in the limit of a zero value leading to a homogeneous incip-⁶⁶⁷ ience of boiling crisis all over the heated plate: the flow is "frozen". On the opposite, large values ⁶⁶⁸ of N_x correspond to a strong variation in the vertical direction; boiling crisis is expected to happen ⁶⁶⁹ in the form of dry spots localized downstream the plate. These two predicted regimes are confirmed ⁶⁷⁰ by experiments as presented in Figure 12. In terms of heat removal, N_x can also be interpreted as ⁶⁷¹ the efficiency of the system to release the input of energy from the heater in the streamwise direction.

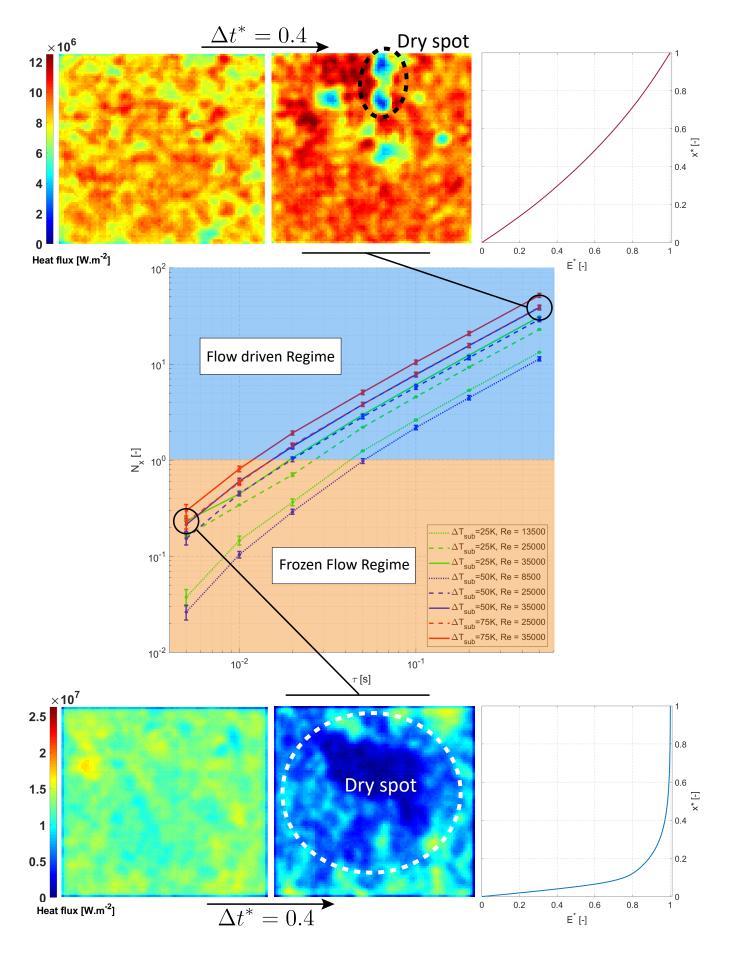


Figure 12: Boiling and energy patterns for different values of N_x . The maps represent the heat flux pattern at the boiling crisis (right maps) and 0.4 τ prior the boiling crisis (left maps). The right curves represent the energy density distribution $E^*(x^*)$ at the boiling crisis. The water flows upwards and the conditions are $\Delta T_{sub} = 50 K$, Re = 35000 and p = 1 bar.

For the experiments presented by Kossolapov et al. in [9], the heating cell is 1 cm in length. 673 For conditions of Re = 35000 and $\Delta T_{sub} = 75 K$, the frozen flow regime is observed for a time 674 period $\tau \leq 10ms$ while the flow driven regime happens for $\tau \geq 20ms$. One expects these values to 675 be modified by a change in the heater length. Other experiments have been conducted using the 676 same channel and similar thermohydraulic conditions but with a longer heater, 4 cm in length. The 677 quantity N_x becomes equal to 0.73 when the power excursion period $\tau = 50$ ms, now corresponding to 678 the frozen flow regime. The space-variation of the volumetric energy density rise at $t=t_{CHF}$ and the 679 heat flux field measured on the heated plate obtained for these conditions are presented in Figure 13. 680 The energy profile shows a plateau for x^* greater than 0.4. The heat flux distribution clearly reveals 681 two distinct areas. At the inlet part of the plate $(x^* \leq 0.4)$ a large amount of heat flux is released 682 in the fluid while beyond $x^* = 0.4$, many spots of small heat flux are visible revealing that dry spots 683 are present in this area. 684

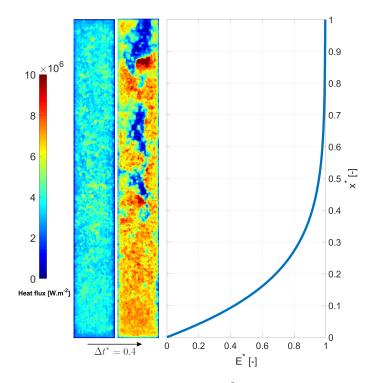


Figure 13: Boiling and energy patterns for a $4 \times 0.6 \ cm^2$ heating cell. The maps represent the heat flux pattern at the boiling crisis (right map) and 0.4τ prior the boiling crisis (left map). The right curve represents the energy density distribution $E^*(x^*)$ at the boiling crisis. The water flows upwards and the conditions are $\Delta T_{sub} = 50 \ K$, Re = 35000 and $p = 1 \ bar$, $\tau = 50 \ ms$ ($N_x = 0.73$).

From the previous analysis, N_x appears to be a relevant quantity, more than the period τ , to predict the location for boiling crisis to occur, i.e. homogeneously along the heater or localized downstream the heater. Indeed, considering the same time period as in Figure 13, *i.e.* $\tau = 50$ ms but the 1 cm-long heater, boiling crisis occurs, localized only at the downstream extremity of the heater. This feature is not surprising as these experimental conditions correspond to $N_x = 5$. This conclusion may be useful for industrial applications, particularly for nuclear industry. If considering for instance, an accidental scenario of the BORAX-type, the computation of N_x would give information on the particular zones where the fuel rods could be damaged. If the thermohydraulic conditions and the power escalation period correspond to a high value of the N_x group, reaching the boiling crisis would only damage the downstream part of the core, whereas a small value of N_x would imply the possible failure of the entire core.

$_{696}$ 4.3.2 Interpretation of N_y and experimental evidences

⁶⁹⁷ The non-dimensional group N_y represents the ratio between two characteristic times, τ the power ⁶⁹⁸ excursion period, and δ/v_m which is the time needed for a fluid particle, located at the boundary ⁶⁹⁹ bulk-mantle, to travel away from the wall over a length δ at the velocity v_m . Qualitatively, N_y is the ⁷⁰⁰ number characterizing the efficiency of the system to transfer energy from the mantle to the bulk in ⁷⁰¹ the direction normal to the wall via the turbulent fluctuations of the normal velocity. N_y increases ⁷⁰² with the Reynolds number.

703

The role of this group N_y can be illustrated considering the results obtained in 1964 with the 704 SPERT IV facility [4]. A power pulse was applied in 64 cm tall fuel plates. The fluid was highly 705 subcooled ($\Delta T_{sub} \sim 90$ K) flowing between the fuel plates with a bulk velocity up to $U_{bulk} = 3.7 \text{ m.s}^{-1}$. 706 As the characteristic velocity u_m is much smaller than U_{bulk} , N_x can be highly maximized by $U_{bulk}\tau/L$. 707 All runs conducted with a power escalation period equal to 10 ms, lead to N_x values smaller than 0.1 708 due to the large value of L. This situation corresponds to the "frozen regime". Various tests reported 709 in [4] are presented in Figure 14. All recordings were performed with a similar power input and a 710 time-period τ of ten milliseconds. The only change in the tests was the bulk velocity as indicated in 711 Figure 14. At low velocity (Tests B-23 and B-29), a temperature plateau is observed, 70 K above the 712 saturation temperature. This does not happen for the highest velocities (Tests B-33 and B-39) where 713 smaller temperature excursions are observed. With the increase of the flow rate, a better cooling 714 is achieved as the bulk velocity and the turbulent fluctuations increase. Since N_x is small for these 715 four configurations ($N_x < 0.1$), the streamwise cooling process is always weak and thus cannot be 716 the discriminating phenomenon explaining the different observations. Conversely, with the increase 717 of the flow rate and so of the turbulence, the velocity v_m increases and so N_y and the cooling process 718 normal to wall, preventing the occurrence of boiling crisis for the test B-33 and B-39. 719

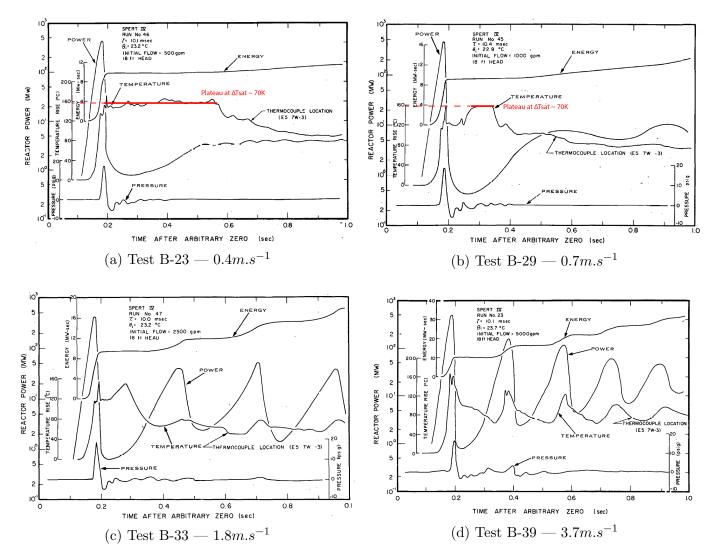


Figure 14: SPERT IV test results for 10 *ms* power excursion period with different flow conditions (adapted from [4]).

Lastly, the flow conditions to be considered for the prediction of boiling crisis deserve a few com-720 ments. Quantities usually mentioned in the literature are either the bulk velocity U_{bulk} [m.s⁻¹], the 721 mass flux $G[kg.m^{-2}.s^{-1}]$ or the Reynolds number Re[-]. Nevertheless, these quantities are relevant 722 if considering the flow in the whole cross-section. As discussed in the present work, for high sub-723 cooling and strong forced convection, physical phenomena involved in the occurrence of boiling crisis 724 are located in the region near the wall, whose characteristic length scale is the mantle thickness δ . 725 Therefore the relevant quantities to be used for these specific conditions should be the wall quantities, 726 namely the wall Reynolds number Re_{τ} [-], the shear velocity u^* $[m.s^{-1}]$ and the viscous sub-layer 727 unit δ_{ν} [m]. 728

729

730 5 Conclusions and Perspectives

We have presented a new model aiming to describe the flow boiling crisis generated by exponential power transients at high subcooling and atmospheric pressure. The model is based on the novel experimental insight offered by the work of by Kossolapov et al. who used synchronized high speed video and IR thermometry with high resolution diagnostics [9]. Particularly, this model accounts for the mechanism of nucleation and condensation cycles (NCCs) not previously taken into account to model boiling crisis for such conditions of high subcooling. The model includes heat removal contributions in both streamwise and normal directions using turbulent flow characteristics.

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The present model makes use of a physical *a priori* unknown quantity which is the mantle 739 thickness δ . Using a non-dimensional approach, we have shown that this quantity verifies a simple 740 mathematical relation involving the operating conditions and a unique experimental tuning constant 741 δ_{∞}^{++} common to all investigated tests. The fit between the experimental points and the latter relation 742 is excellent for highly subcooling conditions, *i.e.* for 50 K of subcooling and more, which are the 743 most relevant for nuclear safety applications. The fitting is also excellent at 25 K of subcooling for 744 long periods, *i.e.* for $\tau/\tau_x > 1$, which reveals the validity limit in term of subcooling of our approach. 745 The quality of this fitting shows that from this simple formulation, the model is able to take into 746 consideration the different operating parameters explaining the role of each. Moreover, the two non-747 dimensional groups N_x and N_y arising in the model provide physical explanations for experimental 748 observations. The group N_x appears as a predicting tool to explain spatial occurrence of the boiling 749 crisis on the heating wall, *i.e.* homogeneously along or localized downstream the heater. This result 750 can be usefully applied for instance in nuclear safety as it allows to predict the localization of the 751 failed fuel during an accident. The group N_y , quantifies the contribution of heat removal in the 752 transverse direction due to turbulent velocity fluctuations. It brings into light effects observed in 753 large-scale reactor tests. 754

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The present work investigates exponential power transients and homogeneous heat flux fields. An extension to other types of transients and to heterogeneous heat flux fields is however possible as the current mathematical formulation of the model allows it. Finally, a better understanding of the constant δ_{∞}^{++} would enable the present model to become fully predictive. The impact of the pressure and on the parameter λ are currently in progress.

761 Acknowledgment

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⁸⁴⁷ A Appendix - DNS analysis

⁸⁴⁸ A.1 Computation method of the determination of the velocity v_m

⁸⁴⁹ DNS simulations performed by Moser et al. [33] investigated turbulent flows inside a rectangular ⁸⁵⁰ channel. Their data yield Probability Density Functions (PDF) as a function of the distance to the ⁸⁵¹ wall and for three values of the Re_{τ} parameter (180, 395 and 590). Graham et al. [32] performed ⁸⁵² similar DNS simulations with $Re_{\tau} = 1000$ and made available instantaneous velocity fields in steady-⁸⁵³ state conditions.

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For Re_{τ} equals 180, 395 and 590, Moser et al. propose in their data sets, the PDFs of v' for different y^+ from the wall to the channel centerline. The use of equation (19) at each available y^+ enables then to compute the expected value v_m^+ for the three values of Re_{τ} (see figure 16a).

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For Re_{τ} equals 1000, Graham et al. propose in their database the full velocity field of their 859 simulation. The simulation domain consists of a mesh made of $2048 \times 512 \times 1436$ nodes and the 860 database presents 4000 snapshots of the field. In the x and z directions, the domain is periodic. The 861 authors provide statistic quantities of the flow such as the mean velocities or the Root Mean Square 862 (RMS) compounds, but not the actual PDF needed to calculate v_m . It is then necessary to first 863 compute the expected value v_m from the raw statistics. In order to have enough points to compute 864 the expected value, we assume the ergodic hypothesis: for a given y coordinate, a quantity X verifies 865 $\overline{X} = \langle X \rangle_{x,z}$, which are respectively the temporal average for a given position and the space average 866 in a plan x - z for a given time. By symmetry, we will only investigate half of the channel in the 867 y direction, *i.e.* between the wall and the channel centerline. A node over two will be taken into 868 account in this direction as this reduction gives a satisfactorily fine information on the field v_m and 869 reduces the computation time. For each y coordinate analyzed, all the x - z nodes of the y-constant 870 layer are used to compute the expected value. We also combine the data of three randomly chosen 871

time steps in order to smooth a potential punctual statistic event, such as vortices. Then, each value v_m is obtained from a statistic made of $2048 \times 1536 \times 3$ points, *i.e.* more than nine millions points. The following procedure aims to validate the fact that this sample size is satisfactorily large.

To investigate the statistical convergence, let us define two quantities: the normalized mean transverse velocity V^+ and the two v_m^+ components computed with the positive and negative fluctuations. From a finite statistic sample of N observations of normalized transverse velocities v_n^+ , V^+ is defined as

$$V^{+} = \mathbb{E}(v' \mid \mathbb{R}) = \sum_{n=1}^{N} \frac{v_n^{+}}{N}$$
(26)

⁸⁸⁰ This quantity theoretically equals zero. We also define two v_m^+ components

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$$v_{m,v'>0}^{+} = \mathbb{E}(v' \mid \mathbb{R}^{+}) = \frac{1}{N} \sum_{v_{n}^{+}>0} v_{n}^{+} \qquad v_{m,v'<0}^{+} = \mathbb{E}(v' \mid \mathbb{R}^{-}) = -\frac{1}{N} \sum_{v_{n}^{+}<0} v_{n}^{+}$$
(27)

where $v_{m,v'>0}^+$ is v_m^+ computed with the positive fluctuations and $v_{m,v'<0}^+$ is v_m^+ computed with the negative fluctuations. These values theoretically compensate each other. In figure 15, we present the value taken by these three quantities as a function of the sample size N.

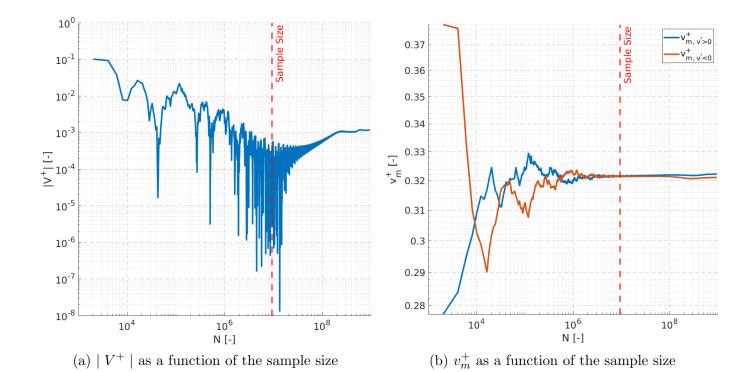


Figure 15: Statistic convergence analysis for the set $Re_{\tau} = 1000$ of Graham et al. [32] and $y^+ = 41$. The quantities are plotted as functions of the sample size N. The dashed line corresponds to the sample size taken for the upcoming computation, *i.e.* $2048 \times 1536 \times 3$.

Qualitatively, $v_{m,v'>0}^+$ and $v_{m,v'<0}^+$ fluctuate for small values of N and converge to a common value for larger values. Particularly, they have converged for the sample size $2048 \times 1536 \times 3$ (see figure 15b) which is represented by the vertical dashed line. More quantitative criteria can be assessed with the mean velocity. First of all, for the sample size $2048 \times 1536 \times 3$, the absolute value taken by the mean velocity is negligible compared to the characteristic velocity of the channel flow, *i.e.* the shear velocity u^* : $|V^+| = |V| / u^* < 10^{-3}$ (see figure 15a). Moreover, the mean velocity is negligible compared to our quantity of interest, v_m , which is the most relevant criterion for our computations:

$$\frac{|V^+|}{v_m^+} < 10^{-2} \tag{28}$$

This confirms that for a sample size of $2048 \times 1536 \times 3$ observations, V^+ has converged to zero. Thus this sample size is adequate for the calculation of v_m^+ . Lastly, we will take v_m^+ as the average of the two definitions, $v_m^+ = \frac{1}{2}(v_{m,v'>0}^+ + v_{m,v'<0}^+)$.

⁸⁹⁵ A.2 Comparative study on the methods to compute v_m

After having defined the method to compute the expected value v_m , let us compare our results with the ones of Weisman and Pei, and of Pasamehmetoglu which need less computing resources. The formulation of their characteristic velocity is:

$$\mathbb{E}(v' - v_v \mid [v_v, +\infty]) = \int_{v_v}^{+\infty} (v' - v_v) P(v') \, dv'$$
(29)

where the PDF P(v') is defined with an assumed analytic expression and v_v the vapor ejection 899 velocity, which is taken null in our case as explained in section 3.3. Pasamehmetoglu assumed a 900 hyperbolic distribution, $P(v') \propto (1/v')^n$ with n, an adjustable empirical coefficient taken in the 901 interval $[2, +\infty)$. In order to fit his model with the experimental data set, n is taken equal to 4. In 902 our case, v_v is taken null and the computation of the expected value Eq. (29) corresponds to the 903 integral $\int_0^{+\infty} dx/x^{n-1}$, which diverges. Consequently, the approach of Pasamehmetoglu cannot be 904 used in our case. In their approach, Weisman and Pei assumed that P(v') has a Gaussian distribution 905 everywhere in the domain, *i.e.* $\forall y^+ \in [0, Re_{\tau}]$: 906

$$P_{wp}(v') = \frac{e^{-\frac{1}{2}\left(\frac{v'}{v_{rms}}\right)^2}}{v_{rms}\sqrt{2\pi}}$$
(30)

This assumption is relevant in the bulk, but is not true near the wall where anisotropy effects deviate the probability density function from a Gaussian distribution. In order to quantify the discrepancy between this assumption and the actual fluctuations extracted from the DNS data, we compare the expected values $v_m = \mathbb{E}(v' | \mathbb{R}^+)$ computed with the Gaussian distribution $(v_{m,wp}^+)$ with the ones computed with DNS data as above (v_m^+) . The relative discrepancy is defined as

$$\frac{|v_m^+ - v_{m,wp}^+|}{v_m^+} \tag{31}$$

The comparison is plotted in Fig. 16b. A maximum difference of about 50 %, is observed at $y^+ = 5$ and reduces as the distance increases, being about 5 % at $y^+ = 50$. As the present study concerns near wall phenomena, we decided to use DNS data to compute v_m . This calculation for different values of y^+ and for the four Re_{τ} gives the parametric function presented in figure 16a.

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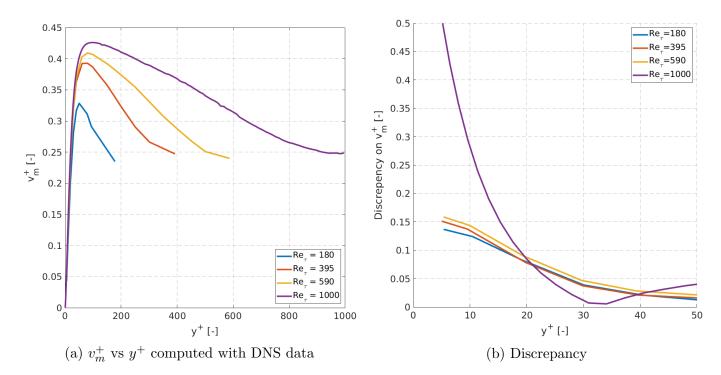


Figure 16: (a) Dimensionless velocity v_m^+ as a function of the dimensionless normal coordinate y^+ calculated for $Re_{\tau} = 180, 395, 590, 1000$ with DNS data of Moser et al. [33] and Graham et al. [32]. (b) Discrepancies with the Gaussian distribution assumption.

917 B Appendix - Uncertainty

⁹¹⁸ The uncertainty of δ is defined in the present work as

$$\Delta \delta = \sqrt{(\Delta \delta_m)^2 + (\Delta \delta_t)^2 + (\sigma_\delta)^2} \tag{32}$$

⁹¹⁹ $\Delta \delta_m$ is the uncertainty resulted from the propagated measurement uncertainty on the heat flux to ⁹²⁰ water. As reported in Kossolapov et al. [9], the measurement uncertainty of the heat flux to water ⁹²¹ $\delta q''_w$ is mainly due to the uncertainty of the current and voltage measurements. The latter generates ⁹²² an uncertainty in the computed value of the mantle thickness. To compute this uncertainty $\Delta \delta_m$, the ⁹²³ algorithm described in Figure 7 is computed using as input the heat flux $(q''_w \pm \delta q''_w)(t)$. The difference ⁹²⁴ between the output and the previously computed δ defines then the measurement uncertainty $\Delta \delta_m$.

 $\Delta \delta_t$ is the temporal uncertainty due to the boiling crisis frame assessment [9]. The latter is due to the frame rate of the IR camera which implies that the occurrence of the boiling crisis can only be assessed within a small, but non-null, time interval. To compute this uncertainty $\Delta \delta_t$, the algorithm described in Figure 7 is computed using as integration interval the interval [0, $t_{CHF} \pm \delta t$], with $\delta t = 0.4$ ms, the inverse of the camera frame rate. The difference between the output and the previously computed δ defines then the temporal uncertainty $\Delta \delta_t$.

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Finally, as each working point was tested three times, σ_{δ} is the standard deviation of the three corresponding values of the mantle thickness, quantifying the repeatably of the process.